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# **D-Wave Hybrid**

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A general, minimal Python framework for building hybrid asynchronous decomposition samplers for quadratic unconstrained binary optimization (QUBO) problems.

*dwave-hybrid* facilitates three aspects of solution development:

- Hybrid approaches to combining quantum and classical compute resources
- Evaluating a portfolio of algorithmic components and problem-decomposition strategies
- Experimenting with workflow structures and parameters to obtain the best application results

The framework enables rapid development and insight into expected performance of productized versions of its experimental prototypes.

Your optimized algorithmic components and other contributions to this project are welcome!



# CHAPTER 1

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## Example

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```
import dimod
import hybrid

# Construct a problem
bqm = dimod.BinaryQuadraticModel({}, {'ab': 1, 'bc': -1, 'ca': 1}, 0, dimod.SPIN)

# Define the workflow
iteration = hybrid.RacingBranches(
    hybrid.Identity(),
    hybrid.InterruptableTabuSampler(),
    hybrid.EnergyImpactDecomposer(size=2)
    | hybrid.QPUSubproblemAutoEmbeddingSampler()
    | hybrid.SplatComposer()
) | hybrid.ArgMin()
workflow = hybrid.LoopUntilNoImprovement(iteration, convergence=3)

# Solve the problem
init_state = hybrid.State.from_problem(bqm)
final_state = workflow.run(init_state).result()

# Print results
print("Solution: sample={.samples.first}".format(final_state))
```





## 2.1 Introduction

**dwave-hybrid** provides a framework for iterating arbitrary-sized sets of samples through parallel solvers to find an optimal solution.

For the documentation of a particular code element, see the *Reference Documentation* section. This introduction gives an overview of the package; steps you through using it, starting with running a provided hybrid solver that handles arbitrary-sized QUBOs; and points out the way to developing your own components in the framework.

- *Overview* presents the framework and explains key concepts.
- *Using the Framework* shows how to use the framework. You can quickly get started by using a provided reference sampler built with this framework, Kerberos, to solve a problem too large to `minor-embed` on a D-Wave system. Next, use the framework to build (hybrid) workflows; for example, a solver similar to `qbsolv`, which can employ tabu search on a whole problem while submitting parts of the problem to a D-Wave system.
- *Developing New Components* guides you to developing your own hybrid components.

### 2.1.1 Overview

The *dwave-hybrid* framework enables you to quickly design and test workflows that iterate sets of samples through samplers to solve arbitrary QUBOs. Large problems can be decomposed and two or more solution techniques can run in parallel.

The *Schematic Representation* figure below shows an example configuration. Samples are iterated over four parallel solvers. The top **branch** represents a classical tabu search that runs on the entire problem until interrupted by another branch completing. These use different decomposers to parcel out parts of the current sample set (iteration  $i$ ) to samplers such as a D-Wave system (second-highest branch) or another structure of parallel simulated annealing and tabu search. A generic representation of a branch's components—decomposer, sampler, and composer—is shown in the lowest branch. A user-defined criterion selects from current samples and solver outputs a sample set for iteration  $i + 1$ .

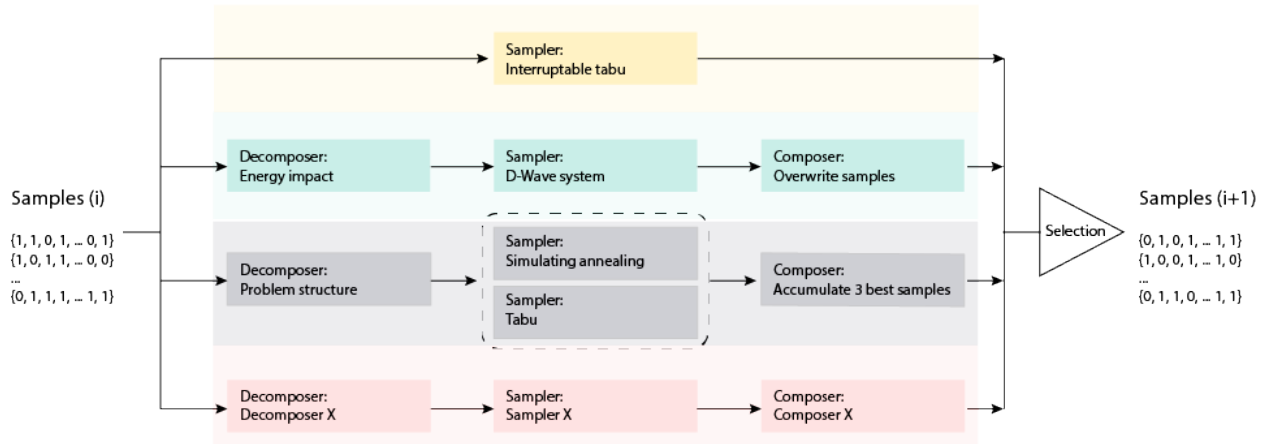


Fig. 1: Schematic Representation

You can use the framework to run a provided hybrid solver or to configure workflows using provided components such as tabu samplers and energy-based decomposers.

You can also use the framework to build your own components to incorporate into your workflow.

## 2.1.2 Using the Framework

This section helps you quickly use a provided reference sampler to solve arbitrary-sized problems and then shows you how to build (hybrid) workflows using provided components.

### Reference Hybrid Sampler: Kerberos

*dwave-hybrid* includes a reference example sampler built using the framework: Kerberos is a dimod-compatible hybrid asynchronous decomposition sampler that enables you to solve problems of arbitrary structure and size. It finds best samples by running in parallel tabu search, simulated annealing, and D-Wave subproblem sampling on problem variables that have high-energy impact.

The example below uses Kerberos to solve a large QUBO.

```
>>> import dimod
>>> from hybrid.reference.kerberos import KerberosSampler
>>> with open('./problems/random-chimera/8192.01.qubo') as problem:
...     bqm = dimod.BinaryQuadraticModel.from_coo(problem)
>>> len(bqm)
8192
>>> solution = KerberosSampler().sample(bqm, max_iter=10, convergence=3) # doctest: +SKIP
-> +SKIP
>>> solution.first.energy # doctest: +SKIP
-4647.0
```

### Building Workflows

As shown in the *Overview* section, you build hybrid solvers by arranging components such as samplers in a workflow.

## Building Blocks

The basic components—building blocks—you use are based on the *Runnable* class: decomposers, samplers, and composers. Such components input a set of samples, a *SampleSet*, and output updated samples. A *State* associated with such an iteration of a component holds the problem, samples, and optionally additional information.

The following example demonstrates a simple workflow that uses just one *Runnable*, a sampler representing the classical tabu search algorithm, to solve a problem (fully classically, without decomposition). The example solves a small problem of a triangle graph of nodes identically coupled. An initial *State* of all-zero samples is set as a starting point. The solution, *new\_state*, is derived from a single iteration of the *TabuProblemSampler Runnable*.

```
>>> import dimod
>>> # Define a problem
>>> bqm = dimod.BinaryQuadraticModel.from_ising({}, {'ab': 0.5, 'bc': 0.5, 'ca': 0.5})
>>> # Set up the sampler with an initial state
>>> sampler = TabuProblemSampler(tenure=2, timeout=5)
>>> state = State.from_sample({'a': 0, 'b': 0, 'c': 0}, bqm)
>>> # Sample the problem
>>> new_state = sampler.run(state).result()
>>> print(new_state.samples)                                # doctest: +SKIP
  a  b  c  energy  num_occ.
0 +1 -1 -1    -0.5         1
['SPIN', 1 rows, 1 samples, 3 variables]
```

## Flow Structuring

The framework provides classes for structuring workflows that use the “building-block” components. As shown in the *Overview* section, you can create a *branch* of *Runnable* classes; for example *decomposer | sampler | composer*, which delegates part of a problem to a sampler such as the D-Wave system.

The following example shows a branch comprising a decomposer, local Tabu solver, and a composer. A 10-variable binary quadratic model is decomposed by the energy impact of its variables into a 6-variable subproblem to be sampled twice. An initial state of all -1 values is set using the utility function *min\_sample()*.

```
>>> import dimod                                # Create a binary quadratic model
>>> bqm = dimod.BinaryQuadraticModel({t: 0 for t in range(10)},
...                                  {(t, (t+1) % 10): 1 for t in range(10)},
...                                  0, 'SPIN')
>>> branch = (EnergyImpactDecomposer(size=6, min_gain=-10) |
...           TabuSubproblemSampler(num_reads=2) |
...           SplatComposer())
>>> new_state = branch.next(State.from_sample(min_sample(bqm), bqm))
>>> print(new_state.subsamples)                  # doctest: +SKIP
  4  5  6  7  8  9  energy  num_occ.
0 +1 -1 -1 +1 -1 +1    -5.0         1
1 +1 -1 -1 +1 -1 +1    -5.0         1
['SPIN', 2 rows, 2 samples, 6 variables]
```

Such *Branch* classes can be run in parallel using the *RacingBranches* class. From the outputs of these parallel branches, *ArgMin* selects a new current sample. And instead of a single iteration on the sample set, you can use the *Loop* to iterate a set number of times or until a convergence criteria is met.

This example of *Racing Branches* solves a binary quadratic model by iteratively producing best samples. Similar to *qbsolv*, it employs both tabu search on the entire problem and a D-Wave system on subproblems. In addition to building-block components such as employed above, this example also uses infrastructure classes to manage the decomposition and parallel running of branches.

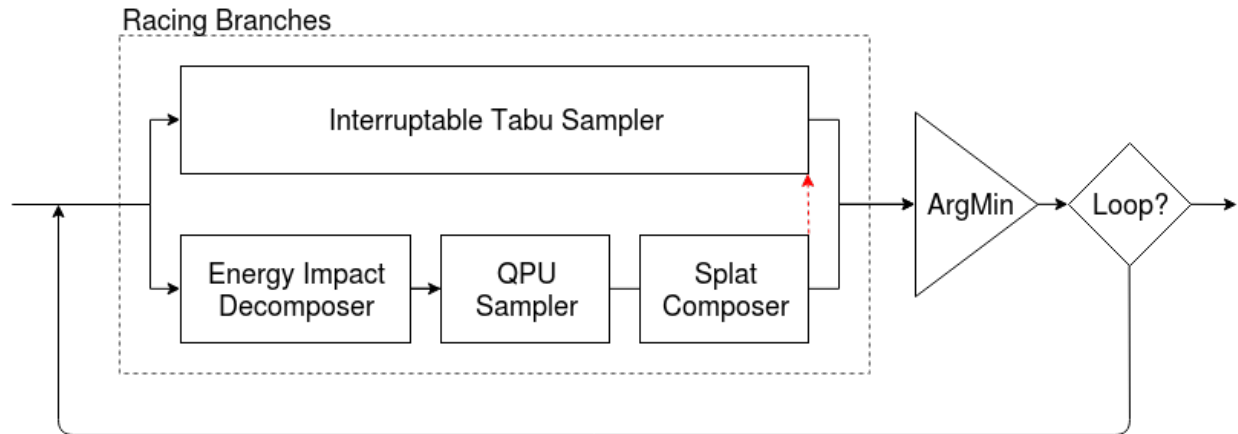


Fig. 2: Racing Branches

```

import dimod
import hybrid

# Construct a problem
bqm = dimod.BinaryQuadraticModel({}, {'ab': 1, 'bc': -1, 'ca': 1}, 0, dimod.SPIN)

# Define the workflow
iteration = hybrid.RacingBranches(
    hybrid.Identity(),
    hybrid.InterruptableTabuSampler(),
    hybrid.EnergyImpactDecomposer(size=2)
    | hybrid.QPUSubproblemAutoEmbeddingSampler()
    | hybrid.SplatComposer()
) | hybrid.ArgMin()
workflow = hybrid.LoopUntilNoImprovement(iteration, convergence=3)

# Solve the problem
init_state = hybrid.State.from_problem(bqm)
final_state = workflow.run(init_state).result()

# Print results
print("Solution: sample={}.samples.first".format(final_state))

```

## Flow Refining

The framework enables quick modification of work flows to improve solutions and performance. For example, after verifying the *Racing Branches* workflow above on its small problem, you might make a series of modifications such as the examples below to better fit it to problems with large numbers of variables.

1. Configure a decomposition window that moves down a fraction of problem variables, ordered from highest to lower energy impact, and submit those subproblems to the D-Wave system while tabu searches globally. This example submits 50-variable subproblems on up to 15% of the total variables.

```

# Redefine the workflow: a rolling decomposition window
subproblem = hybrid.EnergyImpactDecomposer(size=50, rolling_history=0.15)
subsampler = hybrid.QPUSubproblemAutoEmbeddingSampler() | hybrid.SplatComposer()

```

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```
iteration = hybrid.RacingBranches(
    hybrid.InterruptableTabuSampler(),
    subproblem | subsampler
) | hybrid.ArgMin()

workflow = hybrid.LoopUntilNoImprovement(iteration, convergence=3)
```

2. Instead of sequentially producing a sample per subproblem, a further modification might be to process all the subproblems in parallel and merge the returned samples. Here the *EnergyImpactDecomposer* is iterated until it raises a *EndOfStream()* exception when it reaches 15% of the variables, and then all the 50-variable subproblems are submitted to the D-Wave system.

```
# Redefine the workflow: parallel subproblem solving for a single sample
subproblem = hybrid.Unwind(
    hybrid.EnergyImpactDecomposer(size=50, rolling_history=0.15)
)

subsampler = hybrid.Map(
    hybrid.QPUSubproblemAutoEmbeddingSampler()
) | hybrid.Reduce(
    hybrid.Lambda(merge_substates)
) | hybrid.SplatComposer()
```

3. Change the criterion for selecting subproblems. By default, the variables are selected by maximal energy impact but selection can be better tailored to a problem's structure.

For example, for binary quadratic model representing the problem graph shown in the *Traversal by Energy Impact* graphic, if you select a subproblem size of four, these nodes selected by descending energy impact are not directly connected (no shared edges, and might not represent a local structure of the problem).

## Additional Examples

### Tailoring State Selection

The next example tailors a state selector for a sampler that does some post-processing and can alert upon suspect samples. Sampler output modified by ellipses (“...”) for readability is shown below for an Ising model of a triangle problem with zero biases and interactions all equal to 0.5. The first of three *State* classes is flagged as problematic using the *info* field:

```
[{..., 'samples': SampleSet(rec.array([[0, 1, 0], 0., 1])), ..., ['a', 'b', 'c'], {
  ↳ 'Postprocessor': 'Excessive chain breaks', 'SPIN'}),
{..., 'samples': SampleSet(rec.array([[1, 1, 1], 1.5, 1])), ..., ['a', 'b', 'c'], {},
  ↳ 'SPIN'}),
{..., 'samples': SampleSet(rec.array([[0, 0, 0], 0., 1])), ..., ['a', 'b', 'c'], {},
  ↳ 'SPIN'}]]
```

This code snippet defines a metric for the key argument in *ArgMin*:

```
def preempt(si):
    if 'Postprocessor' in si.samples.info:
        return math.inf
    else:
        return si.samples.first.energy
```

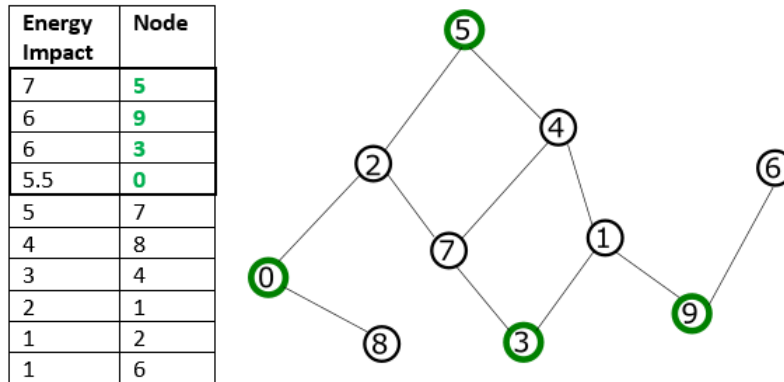


Fig. 3: Traversal by Energy Impact

Configuring a mode of traversal such as breadth-first (BFS) or priority-first selection (PFS) can capture features that represent local structures within a problem.

```
# Redefine the workflow: subproblem selection
subproblem = hybrid.Unwind(
    hybrid.EnergyImpactDecomposer(size=50, rolling_history=0.15,
    ↪traversal='bfs'))
```

These two selection modes are shown in the *Traversal by BFS or PFS* graphic. BFS starts with the node with maximal energy impact, from which its graph traversal proceeds to directly connected nodes, then nodes directly connected to those, and so on, with graph traversal ordered by node index. In PFS, graph traversal selects the node with highest energy impact among unselected nodes directly connected to any already selected node.

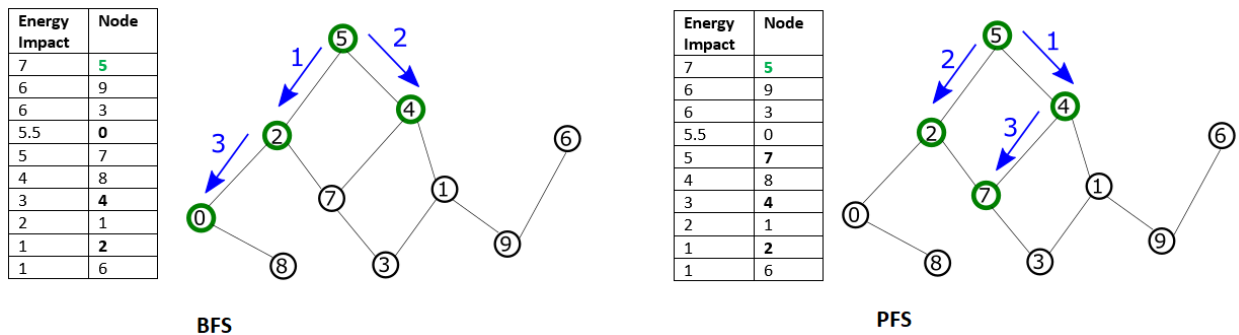


Fig. 4: Traversal by BFS or PFS

Using the defined key on the above input, `ArgMin` finds the state with the lowest energy (zero) excluding the flagged state (which also has energy of zero):

```
>>> ArgMin(key=preempt).next(states)      # doctest: +SKIP
{'problem': BinaryQuadraticModel({'a': 0.0, 'b': 0.0, 'c': 0.0}, {'(a', 'b)': 0.5, ('b
↪', 'c)': 0.5, ('c', 'a)': 0.5},
0.0, Vartype.SPIN), 'samples': SampleSet(rec.array([[0, 0, 0], 0., 1]),
dtype=[('sample', 'i1', (3,)), ('energy', '<f8'), ('num_occurrences', '<i4')]), ['a',
↪ 'b', 'c'], {}, 'SPIN')}
```

## Parallel Sampling

The code snippet below uses `Map` to run a tabu search on two states in parallel.

```
>>> Map(TabuProblemSampler()).run(States(                                     # doctest: +SKIP
    State.from_sample({'a': 0, 'b': 0, 'c': 1}, bqm1),
    State.from_sample({'a': 1, 'b': 1, 'c': 0}, bqm2))
>>> _.result()                                                              # doctest: +SKIP
[{'samples': SampleSet(rec.array([[ -1, -1,  1], -0.5, 1]), dtype=[('sample', 'i1', ↪
↪ (3,)),
('energy', '<f8'), ('num_occurrences', '<i4')]), ['a', 'b', 'c'], {}, 'SPIN'),
'problem': BinaryQuadraticModel({'a': 0.0, 'b': 0.0, 'c': 0.0}, {'(a', 'b)': 0.5, ('b
↪', 'c)': 0.5,
('c', 'a)': 0.5}, 0.0, Vartype.SPIN)},
{'samples': SampleSet(rec.array([[ 1,  1, -1], -1., 1]), dtype=[('sample', 'i1', (3,
↪)),
('energy', '<f8'), ('num_occurrences', '<i4')]), ['a', 'b', 'c'], {}, 'SPIN'),
'problem': BinaryQuadraticModel({'a': 0.0, 'b': 0.0, 'c': 0.0}, {'(a', 'b)': 1, ('b',
↪ 'c)': 1,
('c', 'a)': 1}, 0.0, Vartype.SPIN)}]
```

## Logging and Execution Information

You can see detailed execution information by setting the level of logging.

The package supports logging levels TRACE, DEBUG, INFO, WARNING, ERROR, and CRITICAL in ascending order of severity. By default, logging level is set to ERROR. You can select the logging level with environment variable `DWAVE_HYBRID_LOG_LEVEL`.

For example, on a Windows operating system, set this environment variable to INFO level as:

```
set DWAVE_HYBRID_LOG_LEVEL=INFO
```

or on a Unix-based system as:

```
DWAVE_HYBRID_LOG_LEVEL=INFO
```

The previous example above might output something like the following:

```
>>> print("Solution: sample={s.samples.first}".format(s=solution))      # doctest: +SKIP
```

```
2018-12-10 15:18:30,634 hybrid.flow INFO Loop Iteration(iterno=0, best_state_quality=-
↪ 3.0)
2018-12-10 15:18:31,511 hybrid.flow INFO Loop Iteration(iterno=1, best_state_quality=-
↪ 3.0)
```

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```

2018-12-10 15:18:35,889 hybrid.flow INFO Loop Iteration(iterno=2, best_state_quality=-
↪3.0)
2018-12-10 15:18:37,377 hybrid.flow INFO Loop Iteration(iterno=3, best_state_quality=-
↪3.0)
Solution: sample=Sample(sample={'a': 1, 'b': -1, 'c': -1}, energy=-3.0, num_
↪occurrences=1)

```

### 2.1.3 Developing New Components

The *dwave-hybrid* framework enables you to build your own components to incorporate into your workflow.

The key superclass is the *Runnable* class: all basic components—samplers, decomposers, composers—and flow-structuring components such as branches inherit from this class. A *Runnable* is run for an iteration in which it updates the *State* it receives. Typical methods are *run* or *next* to execute an iteration and *stop* to terminate the *Runnable*.

The *Primitives* and *Flow Structuring* sections describe, respectively, the basic *Runnable* classes (building blocks) and flow-structuring ones and their methods. If you are implementing these methods for your own *Runnable* class, see comments in the code.

The *Racing Branches* graphic below shows the top-down composition (tree structure) of a hybrid loop.

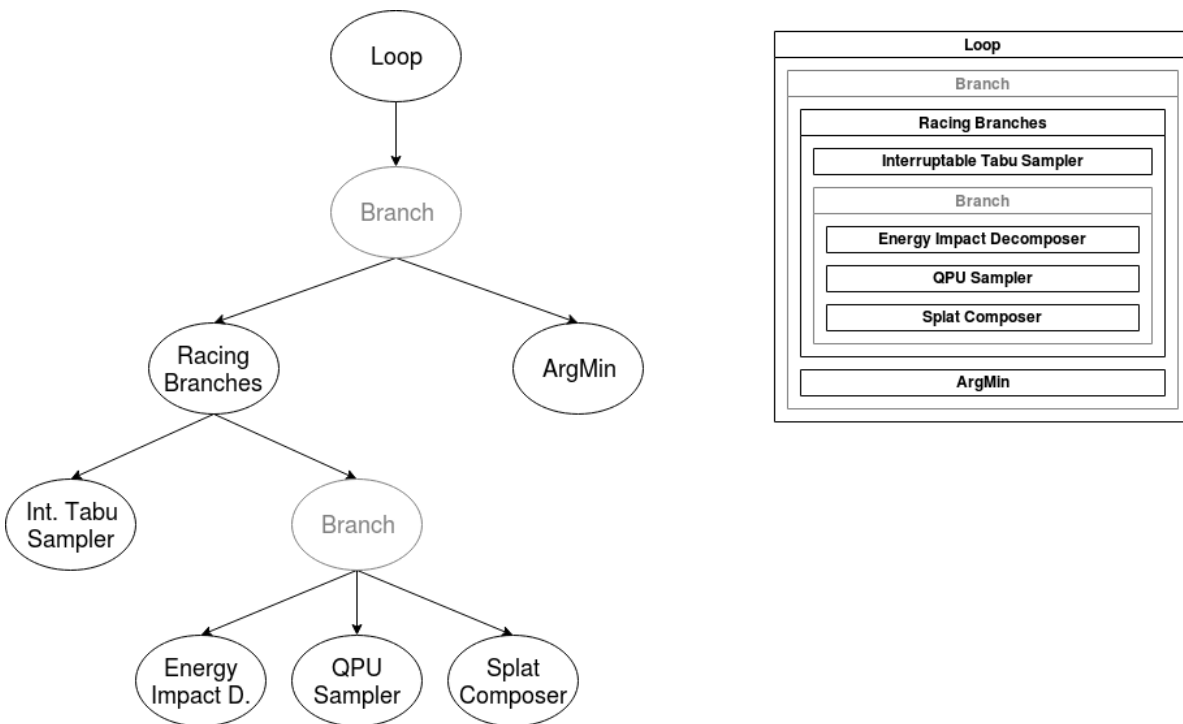


Fig. 5: Top-Down Composition

State traits are verified for all *Runnable* objects that inherit from *StateTraits* or its subclasses. Verification includes:

- (1) Minimal checks of workflow construction (composition of *Runnable* classes)
- (2) Runtime checks



All built-in *Runnable* classes declare state traits requirements that are either independent (for simple ones) or derived from a child workflow. Traits of a new *Runnable* must be expressed and modified at construction time by its parent. When developing new *Runnable* classes, constructing composite traits can be nontrivial for some advanced flow-control runnables.

The *Dimod Conversion* section describes the *HybridRunnable* class you can use to produce a *Runnable* sampler based on a *dimod* sampler.

The *Utilities* section provides a list of useful utility methods.

## 2.2 Reference Documentation

### 2.2.1 Primitives

Basic building-block classes and superclasses for hybrid workflows.

#### Classes

**class Present** (*result=None, exception=None*)

Already resolved *Future* object.

Users should treat this class as just another *Future*, the difference being an implementation detail: *Present* is “resolved” at construction time.

See the example of the *run()* method.

**class Runnable** (*\*\*runopts*)

Components such as samplers and branches that can be run for an iteration.

**Parameters** *\*\*runopts* (*dict*) – Keyword arguments passed down to each *Runnable.run* call.

---

**Note:** The base class *Runnable* does not enforce traits validation. To enable validation, derive your subclass from one of the state structure, I/O dimensionality, or I/O validation mixins in *traits*.

---

#### Examples

This example runs a tabu search on a binary quadratic model. An initial state is manually set to  $x = y = 0, z = 1; a = b = 1, c = 0$  and an updated state is created by running the sampler for one iteration.

```
>>> import dimod # Create a binary quadratic model
>>> bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b'
↳ 'c': 0.0, 'c': 6.0},
...                               (('y', 'x'): 2.0, ('z', 'x'): -4.0, ('z', 'y'
↳ 'y'): -4.0,
...                               ('b', 'a'): 2.0, ('c', 'a'): -4.0, ('c', 'b'
↳ 'c'): -4.0, ('a', 'z'): -4.0},
...                               -1.0, 'BINARY')
>>> # Set up the sampler runnable
>>> sampler = TabuProblemSampler(tenure=2, timeout=5)
>>> # Run one iteration of the sampler
>>> new_state = sampler.next(State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b'
↳ 'c': 1, 'c': 0}, bqm))
>>> print(new_state.samples) # doctest: +SKIP
```

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```

  a b c x y z energy num_occ.
0 1 1 1 1 1 1 -1.0      1
[ 1 rows, 6 variables ]

```

**class State** (\*args, \*\*kwargs)

Computation state passed along a branch between connected components.

State is a *dict* subclass and contains at least keys *samples*, *problem*.

### Examples

```

>>> import dimod # Create a binary quadratic model
>>> bqm = dimod.BinaryQuadraticModel({0: -1, 1: -1}, {(0, 1): 2}, 0.0, dimod.
↳BINARY)
>>> hybrid.core.State.from_sample(hybrid.utils.min_sample(bqm), bqm) # doctest:␣
↳+SKIP
{'problem': BinaryQuadraticModel({0: -1, 1: -1}, {(0, 1): 2}, 0.0, Vartype.
↳BINARY),
 'samples': SampleSet(rec.array([[0, 0], 0., 1]],
   dtype=[('sample', 'i1', (2,)), ('energy', '<f8'), ('num_occurrences', '<i4
↳')]), [0, 1], {}, 'BINARY')}

```

**class States** (\*args)

List of states.

### Properties

<code>Runnable.name</code>	Return the <i>Runnable</i> class name.
<code>SampleSet.first</code>	Sample with the lowest-energy.

### hybrid.core.Runnable.name

`Runnable.name`

Return the *Runnable* class name.

### hybrid.core.SampleSet.first

`SampleSet.first`

Sample with the lowest-energy.

**Raises** `ValueError` – If empty.

### Example

```

>>> sampleset = dimod.ExactSolver().sample_ising({'a': 1}, {'a', 'b': 1})
>>> sampleset.first
Sample(sample={'a': -1, 'b': 1}, energy=-2.0, num_occurrences=1)

```

## Methods

<code>Runnable.dispatch(future, **kwargs)</code>	Dispatch state from resolving <i>future</i> to either <i>next</i> or <i>error</i> methods.
<code>Runnable.error(exc)</code>	Execute one blocking iteration of an instantiated <i>Runnable</i> with an exception as input.
<code>Runnable.init(state, **runopts)</code>	Run prior to the first next/run, with the first state received.
<code>Runnable.halt()</code>	Called by <i>stop()</i> .
<code>Runnable.next(state, **runopts)</code>	Execute one blocking iteration of an instantiated <i>Runnable</i> with a valid state as input.
<code>Runnable.run(state, **kwargs)</code>	Execute the next step/iteration of an instantiated <i>Runnable</i> .
<code>Runnable.stop()</code>	Terminate an iteration of an instantiated <i>Runnable</i> .
<code>State.updated(**kwargs)</code>	Return a (deep) copy of the state, updated from <i>kwargs</i> .
<code>State.from_sample(sample, bqm, **kwargs)</code>	Convenience method for constructing a state from a raw (dict) sample.
<code>State.from_samples(samples, bqm, **kwargs)</code>	Convenience method for constructing a state from raw (dict) samples.

### hybrid.core.Runnable.dispatch

`Runnable.dispatch(future, **kwargs)`

Dispatch state from resolving *future* to either *next* or *error* methods.

**Parameters** *state* (`concurrent.futures.Future`-like object) – *State* future.

Returns state from *next()* or *error()*, or passes through an exception raised there.

Blocks on state resolution and execution of *next()* or *error()*.

### hybrid.core.Runnable.error

`Runnable.error(exc)`

Execute one blocking iteration of an instantiated *Runnable* with an exception as input.

Called when the previous component raised an exception instead of generating a new state.

The default implementation raises again the input exception. *Runnable* errors must be explicitly silenced.

### hybrid.core.Runnable.init

`Runnable.init(state, **runopts)`

Run prior to the first next/run, with the first state received.

Default to NOP.

### hybrid.core.Runnable.halt

`Runnable.halt()`

Called by *stop()*. Override this method (instead of *stop()*) to handle stopping of one blocking call of *next*. Defaults to NOP.

### hybrid.core.Runnable.next

`Runnable.next` (*state*, *\*\*runopts*)

Execute one blocking iteration of an instantiated *Runnable* with a valid state as input.

**Parameters** *state* (*State*) – Computation state passed between connected components.

**Returns** The new state.

**Return type** *State*

#### Examples

This code snippet runs one iteration of a sampler to produce a new state:

```
new_state = sampler.next(core.State.from_sample({'x': 0, 'y': 0}, bqm))
```

### hybrid.core.Runnable.run

`Runnable.run` (*state*, *\*\*kwargs*)

Execute the next step/iteration of an instantiated *Runnable*.

Accepts a state in a *Future*-like object and returns a new state in a *Future*-like object.

#### Parameters

- **state** (*State*) – Computation state future-like object passed between connected components.
- **executor** (*Executor*, optional, default=None) – The *Executor* to which the execution of this block is scheduled. By default *hybrid.concurrency.thread\_executor* is used.

#### Examples

These two code snippets run one iteration of a sampler to produce a new state. The first is an asynchronous call and the second a blocking call.

```
>>> sampler.run(State.from_sample(min_sample(bqm), bqm)) # doctest: +SKIP
<Future at 0x20cbe22ea20 state=running>
```

```
>>> sampler.run(State.from_sample(min_sample(bqm), bqm),
...             executor=hybrid.immediate_executor) # doctest: +SKIP
<Present at 0x20ca68cd2b0 state=finished returned State>
```

### hybrid.core.Runnable.stop

`Runnable.stop` ()

Terminate an iteration of an instantiated *Runnable*.

## hybrid.core.State.updated

`State.updated(**kwargs)`

Return a (deep) copy of the state, updated from *kwargs*.

This method has *dict.update* semantics with immutability of *sorted*. Currently an exception is the *debug* key, if it exists, for which a depth-unlimited recursive merge is executed.

### Example

```
>>> state = State()
>>> state      # doctest: +SKIP
{'problem': None, 'samples': None}
>>> newstate = state.updated(problem="test")
>>> newstate   # doctest: +SKIP
{'problem': 'test', 'samples': None}
```

## hybrid.core.State.from\_sample

**classmethod** `State.from_sample(sample, bqm, **kwargs)`

Convenience method for constructing a state from a raw (dict) sample.

Energy is calculated from the binary quadratic model (BQM), and *State.problem* is also set to that BQM.

### Example

```
>>> import dimod
>>> bqm = dimod.BQM.from_ising({}, {'ab': 0.5, 'bc': 0.5, 'ca': 0.5})
>>> state = State.from_sample({'a': -1, 'b': -1, 'c': -1}, bqm)
```

## hybrid.core.State.from\_samples

**classmethod** `State.from_samples(samples, bqm, **kwargs)`

Convenience method for constructing a state from raw (dict) samples.

Per-sample energy is calculated from the binary quadratic model (BQM), and *State.problem* is set to the BQM.

### Example

```
>>> import dimod
>>> bqm = dimod.BQM.from_ising({}, {'ab': 0.5, 'bc': 0.5, 'ca': 0.5})
>>> state = State.from_samples([{'a': -1, 'b': -1, 'c': -1},
...                             {'a': -1, 'b': -1, 'c': 1}], bqm)
```

## 2.2.2 Samplers

Classical and quantum *Runnable* *dimod* samplers for problems and subproblems.

## Classes

**class QPUSubproblemExternalEmbeddingSampler** (*num\_reads=100*, *qpu\_sampler=None*,  
*qpu\_params=None*, *\*\*runopts*)

A quantum sampler for a subproblem with a defined minor-embedding.

---

**Note:** Externally supplied embedding must be present in the input state.

---

**Parameters**

- **num\_reads** (*int*, *optional*, *default=100*) – Number of states (output solutions) to read from the sampler.
- **qpu\_sampler** (*dimod.Sampler*, *optional*, *default=DWaveSampler()*) – Quantum sampler such as a D-Wave system.
- **qpu\_params** (*dict*) – Dictionary of keyword arguments with values that will be used on every call of the QPU sampler.

See *Examples*.

**class QPUSubproblemAutoEmbeddingSampler** (*num\_reads=100*, *qpu\_sampler=None*,  
*qpu\_params=None*, *\*\*runopts*)

A quantum sampler for a subproblem with automated heuristic minor-embedding.

**Parameters num\_reads** (*int*, *optional*, *default=100*) – Number of states (output solutions) to read from the sampler.

**:param qpu\_sampler** (*dimod.Sampler*, *optional*, **default=:class:'AutoEmbeddingComposite'(:class:'DWaveSampler'())**

Quantum sampler such as a D-Wave system. Subproblems that do not fit the sampler's structure are minor-embedded on the fly with `AutoEmbeddingComposite`.

**Parameters qpu\_params** (*dict*) – Dictionary of keyword arguments with values that will be used on every call of the QPU sampler.

See *Examples*.

**class SimulatedAnnealingSubproblemSampler** (*num\_reads=None*, *num\_sweeps=1000*,  
*beta\_range=None*,  
*beta\_schedule\_type='geometric'*, *initial\_states\_generator='random'*, *\*\*runopts*)

A simulated annealing sampler for a subproblem.

**Parameters**

- **num\_reads** (*int*, *optional*, *default=len(state.subsamples) or 1*) – Number of states (output solutions) to read from the sampler.
- **num\_sweeps** (*int*, *optional*, *default=1000*) – Number of sweeps or steps.
- **beta\_range** (*tuple*, *optional*) – A 2-tuple defining the beginning and end of the beta schedule, where beta is the inverse temperature. The schedule is applied linearly in beta. Default range is set based on the total bias associated with each node.
- **beta\_schedule\_type** (*string*, *optional*, *default='geometric'*) – Beta schedule type, or how the beta values are interpolated between the given 'beta\_range'. Supported values are: linear and geometric.

- **initial\_states\_generator** (*str*, 'none'/'tile'/'random', *optional*, default='random') – Defines the expansion of input state subsamples into *initial\_states* for the simulated annealing, if fewer than *num\_reads* subsamples are present. See `sample()`.

See *Examples*.

```
class TabuSubproblemSampler (num_reads=None, tenure=None, timeout=100, initial_states_generator='random', **runopts)
```

A tabu sampler for a subproblem.

#### Parameters

- **num\_reads** (*int*, *optional*, default=`len(state.subsamples)` or 1) – Number of states (output solutions) to read from the sampler.
- **tenure** (*int*, *optional*) – Tabu tenure, which is the length of the tabu list, or number of recently explored solutions kept in memory. Default is a quarter of the number of problem variables up to a maximum value of 20.
- **timeout** (*int*, *optional*, default=100) – Total running time in milliseconds.
- **initial\_states\_generator** (*str*, 'none'/'tile'/'random', *optional*, default='random') – Defines the expansion of input state subsamples into *initial\_states* for the Tabu search, if fewer than *num\_reads* subsamples are present. See `sample()`.

See *Examples*.

```
class TabuProblemSampler (num_reads=None, tenure=None, timeout=100, initial_states_generator='random', **runopts)
```

A tabu sampler for a binary quadratic problem.

#### Parameters

- **num\_reads** (*int*, *optional*, default=`len(state.samples)` or 1) – Number of states (output solutions) to read from the sampler.
- **tenure** (*int*, *optional*) – Tabu tenure, which is the length of the tabu list, or number of recently explored solutions kept in memory. Default is a quarter of the number of problem variables up to a maximum value of 20.
- **timeout** (*int*, *optional*, default=100) – Total running time in milliseconds.
- **initial\_states\_generator** (*str*, 'none'/'tile'/'random', *optional*, default='random') – Defines the expansion of input state samples into *initial\_states* for the Tabu search, if fewer than *num\_reads* samples are present. See `sample()`.

See *Examples*.

```
class InterruptableTabuSampler (max_time=None, **tabu)
```

An interruptable tabu sampler for a binary quadratic problem.

#### Parameters

- **num\_reads** (*int*, *optional*, default=1) – Number of states (output solutions) to read from the sampler.
- **tenure** (*int*, *optional*) – Tabu tenure, which is the length of the tabu list, or number of recently explored solutions kept in memory. Default is a quarter of the number of problem variables up to a maximum value of 20.

- **timeout** (*int, optional, default=20*) – Timeout for non-interruptable operation of tabu search. At the completion of each loop of tabu search through its problem variables, if this time interval has been exceeded, the search can be stopped by an interrupt signal or expiration of the *timeout* parameter.
- **initial\_states\_generator** (*str, 'none'/'tile'/'random', optional, default='random'*) – Defines the expansion of input state samples into *initial\_states* for the Tabu search, if fewer than *num\_reads* samples are present. See `sample()`.
- **max\_time** (*float, optional, default=None*) – Total running time in milliseconds.

See *Examples*.

### class RandomSubproblemSampler

A random sample generator for a subproblem.

## Examples

### QPUSubproblemExternalEmbeddingSampler

This example works on a binary quadratic model of two AND gates in series by sampling a BQM representing just one of the gates. Output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated by sampling the subproblem 100 times on a D-Wave system. The execution results shown here were three valid solutions to the subproblem; for example,  $x = 0, y = 1, z = 0$  occurred 22 times.

```
import dimod
import minorminer
from dwave.system.samplers import DWaveSampler
from hybrid.samplers import QPUSubproblemExternalEmbeddingSampler
from hybrid.core import State

# Define a problem and a subproblem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c'
↳ ': 6.0},
                                {'(y', 'x'): 2.0, ('z', 'x'): -4.0, ('z', 'y'): -4.0,
                                ('b', 'a'): 2.0, ('c', 'a'): -4.0, ('c', 'b'): -4.0,
↳ ('a', 'z'): -4.0},
                                -1.0, 'BINARY')
sub_bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0},
↳ {'(x', 'y'): 2.0, ('x', 'z'): -4.0, ('y', 'z'): -
↳ 4.0},
                                -1.0, dimod.Vartype.BINARY)

# Find a minor-embedding for the subproblem
qpu_sampler = DWaveSampler()
sub_embedding = minorminer.find_embedding(list(sub_bqm.quadratic.keys()), qpu_sampler.
↳ edgelist)

# Set up the sampler with an initial state
sampler = QPUSubproblemExternalEmbeddingSampler(num_reads=100)
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
state.update(subproblem=sub_bqm, embedding=sub_embedding)
```



```
# Sample the subproblem on the QPU (REPL)
>>> new_state = sampler.run(state).result()
>>> print(new_state.subsamples.record)
[[([0, 1, 0], -1., 22) ([0, 0, 0], -1., 47) ([1, 0, 0], -1., 31)]
```

## QPUSubproblemAutoEmbeddingSampler

This example works on a binary quadratic model of two AND gates in series by sampling a BQM representing just one of the gates. Output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated by sampling the subproblem 100 times on a D-Wave system. The execution results shown here were four valid solutions to the subproblem; for example,  $x = 0, y = 0, z = 0$  occurred 53 times.

```
import dimod
from hybrid.samplers import QPUSubproblemAutoEmbeddingSampler
from hybrid.core import State

# Define a problem and a subproblem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c': 6.0},
                                {('y', 'x'): 2.0, ('z', 'x'): -4.0, ('z', 'y'): -4.0,
                                 ('b', 'a'): 2.0, ('c', 'a'): -4.0, ('c', 'b'): -4.0,
                                 ('a', 'z'): -4.0},
                                -1.0, 'BINARY')
sub_bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0},
                                     {('x', 'y'): 2.0, ('x', 'z'): -4.0, ('y', 'z'): -4.0},
                                     -1.0, dimod.Vartype.BINARY)

# Set up the sampler with an initial state
sampler = QPUSubproblemAutoEmbeddingSampler(num_reads=100)
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
state.update(subproblem=sub_bqm)
```

```
# Sample the subproblem on the QPU (REPL)
>>> new_state = sampler.run(state).result()
>>> print(new_state.subsamples.record)
[[([0, 0, 0], -1., 53) ([0, 1, 0], -1., 15) ([1, 0, 0], -1., 31) ([1, 1, 1], 1., 1)]
```

## SimulatedAnnealingSubproblemSampler

This example works on a binary quadratic model of two AND gates in series by sampling a BQM representing just one of the gates. Output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated by sampling the subproblem 10 times. The execution results shown here were valid solutions to the subproblem; for example,  $x = 0, y = 1, z = 0$ .

```
import dimod
from hybrid.samplers import SimulatedAnnealingSubproblemSampler
from hybrid.core import State

# Define a problem and a subproblem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c': 6.0},
```

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```

        {('y', 'x'): 2.0, ('z', 'x'): -4.0, ('z', 'y'): -4.0,
         ('b', 'a'): 2.0, ('c', 'a'): -4.0, ('c', 'b'): -4.0, ('c
↪ 'a', 'z'): -4.0},
        -1.0, 'BINARY')
sub_bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0},
↪ {'x', 'y'): 2.0, ('x', 'z'): -4.0, ('y', 'z'): -
4.0},
        -1.0, dimod.Vartype.BINARY)

# Set up the sampler with an initial state
sampler = SimulatedAnnealingSubproblemSampler(num_reads=10)
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
state.update(subproblem=sub_bqm)

```

```

# Sample the subproblem (REPL)
>>> new_state = sampler.run(state).result()
>>> print(new_state.subsamples.record)
[[([0, 1, 0], -1., 1) ([0, 1, 0], -1., 1) ([0, 0, 0], -1., 1)
([0, 0, 0], -1., 1) ([0, 0, 0], -1., 1) ([1, 0, 0], -1., 1)
([1, 0, 0], -1., 1) ([0, 0, 0], -1., 1) ([0, 1, 0], -1., 1)
([1, 0, 0], -1., 1)]

```

## TabuSubproblemSampler

This example works on a binary quadratic model of two AND gates in series by sampling a BQM representing just one of the gates. Output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated by a tabu search on the subproblem. The execution results shown here was a valid solution to the subproblem: example,  $x = 0, y = 1, z = 0$ .

```

import dimod
from hybrid.samplers import TabuSubproblemSampler
from hybrid.core import State

# Define a problem and a subproblem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c
↪ ': 6.0},
        {('y', 'x'): 2.0, ('z', 'x'): -4.0, ('z', 'y'): -4.0,
         ('b', 'a'): 2.0, ('c', 'a'): -4.0, ('c', 'b'): -4.0,
↪ ('a', 'z'): -4.0},
        -1.0, 'BINARY')
sub_bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0},
↪ {'x', 'y'): 2.0, ('x', 'z'): -4.0, ('y', 'z'): -
4.0},
        -1.0, dimod.Vartype.BINARY)

# Set up the sampler with an initial state
sampler = TabuSubproblemSampler(tenure=2, timeout=5)
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
state.update(subproblem=sub_bqm)

```

```

>>> # Sample the subproblem (REPL)
>>> print(new_state.subsamples.record)
[[([0, 1, 0], -1., 1)]

```

## TabuProblemSampler

This example works on a binary quadratic model of two AND gates in series, where output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated by a tabu search. The execution results shown here was a valid solution to the problem: example,  $x = y = z = a = b = c = 1$ .

```
import dimod
from hybrid.samplers import TabuProblemSampler
from hybrid.core import State

# Define a problem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c': 6.0},
                                  {'(y', 'x)': 2.0, ('z', 'x)': -4.0, ('z', 'y)': -4.0,
                                   ('b', 'a)': 2.0, ('c', 'a)': -4.0, ('c', 'b)': -4.0,
                                   ('a', 'z)': -4.0},
                                  -1.0, 'BINARY')

# Set up the sampler with an initial state
sampler = TabuProblemSampler(tenure=2, timeout=5)
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
```

```
# Sample the problem (REPL)
>>> new_state = sampler.run(state).result()
>>> print(new_state.samples)
Response(rec.array([[1, 1, 1, 1, 1, 1], -1., 1]],
          dtype=[('sample', 'i1', (6,)), ('energy', '<f8'), ('num_occurrences', '<i4')],
          ['a', 'b', 'c', 'x', 'y', 'z'], {}, 'BINARY')
```

## InterruptableTabuSampler

This example works on a binary quadratic model of two AND gates in series, where output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated by a tabu search. The execution results shown here was a valid solution to the problem: example,  $x = y = z = a = b = c = 1$ .

```
import dimod
from hybrid.samplers import InterruptableTabuSampler
from hybrid.core import State

# Define a problem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c': 6.0},
                                  {'(y', 'x)': 2.0, ('z', 'x)': -4.0, ('z', 'y)': -4.0,
                                   ('b', 'a)': 2.0, ('c', 'a)': -4.0, ('c', 'b)': -4.0,
                                   ('a', 'z)': -4.0},
                                  -1.0, 'BINARY')

# Set up the sampler with an initial state
sampler = InterruptableTabuSampler(tenure=2, quantum_timeout=30, timeout=5000)
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
```

```

>>> # Sample the problem (REPL)
>>> new_state = sampler.run(state)
>>> new_state
<Future at 0x179eae59898 state=running>
>>> sampler.stop()
>>> new_state
<Future at 0x179eae59898 state=finished returned State>
>>> print(new_state.result())
State(samples=Response(rec.array([[1, 1, 1, 1, 1, 1], -1., 1]],
      dtype=[('sample', 'i1', (6,)), ('energy', '<f8'), ('num_occurrences', '<i4')]),
      ['a', 'b', 'c', 'x', 'y', 'z'], {}, 'BINARY'))

```

## RandomSubproblemSampler

This example works on a binary quadratic model of two AND gates in series by sampling a BQM representing just one of the gates. Output  $z$  of gate  $z = x \wedge y$  connects to input  $a$  of gate  $c = a \wedge b$ . An initial state is manually set with invalid solution  $x = y = 0, z = 1; a = b = 1, c = 0$ . The state is updated with a random sample..

```

import dimod
from hybrid.samplers import RandomSubproblemSampler
from hybrid.core import State

# Define a problem and a subproblem
bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0, 'a': 2.0, 'b': 0.0, 'c': 6.0},
    {('y', 'x'): 2.0, ('z', 'x'): -4.0, ('z', 'y'): -4.0,
     ('b', 'a'): 2.0, ('c', 'a'): -4.0, ('c', 'b'): -4.0,
     ('a', 'z'): -4.0},
    -1.0, 'BINARY')
sub_bqm = dimod.BinaryQuadraticModel({'x': 0.0, 'y': 0.0, 'z': 8.0},
    {('x', 'y'): 2.0, ('x', 'z'): -4.0, ('y', 'z'): -4.0},
    -1.0, dimod.Vartype.BINARY)

# Set up the sampler with an initial state
sampler = RandomSubproblemSampler()
state = State.from_sample({'x': 0, 'y': 0, 'z': 1, 'a': 1, 'b': 1, 'c': 0}, bqm)
state.update(subproblem=sub_bqm)

```

```

# Sample the subproblem a couple of times (REPL)
>>> new_state = sampler.run(state).result()
>>> print(new_state.subsamples.record)
[[[0, 0, 0], -1., 1]]
>>> new_state = sampler.run(state).result()
>>> print(new_state.subsamples.record)
[[[1, 1, 1], 1., 1]]

```

## 2.2.3 Composers

### Class

#### class SplatComposer

A composer that overwrites current samples with subproblem samples.

See *Examples*.

### class GreedyPathMerge

Dialectic-search merge operation [KS]. Generates a path from one input state, representing the thesis, to another input state, representing the antithesis, using a greedy method of single bit flips selected by decreasing energy.

Returns the best sample on the path, which represents the synthesis.

Note: only the lowest-energy sample, is considered from either input state.

See *Examples*.

### References

### Examples

#### SplatComposer

This example runs one iteration of a *SplatComposer* composer, overwriting an initial solution to a 6-variable binary quadratic model of all zeros with a solution to a 3-variable subproblem that was manually set to all ones.

```
import dimod
from hybrid.composers import SplatComposer
from hybrid.core import State, SampleSet
from hybrid.utils import min_sample

bqm = dimod.BinaryQuadraticModel({t: 0 for t in range(6)},
                                 {(t, (t+1) % 6): 1 for t in range(6)},
                                 0, 'BINARY')

composer = SplatComposer()
state0 = State.from_sample(min_sample(bqm), bqm)
state1 = state0.updated(subsamples=SampleSet.from_samples({3: 1, 4: 1, 5: 1}, 'BINARY'
↳, 0.0))

composed_state = composer.run(state1).result()
```

```
>>> print(composed_state.samples)
Response(rec.array([[0, 0, 0, 1, 1, 1], 1, 2]),
          dtype=[('sample', 'i1', (6,)), ('num_occurrences', '<i8'), ('energy', '<i8'
↳)], [0, 1, 2, 3, 4, 5], {}, 'BINARY')
```

#### GreedyPathMerge

This example runs one iteration of a *GreedyPathMerge* composer on a thesis and antithesis *State* to find a ground state of a square graph. By inverting the state of variable *d* and *c* in *samples\_d* and then variable *a* of the lowest energy sample of *samples\_a* (second sample), the composer finds a path between these two samples that contains the ground state shown on the right of the top figure.

```
import dimod
bqm = dimod.BinaryQuadraticModel({}, {'ab': 1.0, 'bc': 1.0, 'cd': 1.0, 'da': 1}, 0,
↳ 'SPIN')
samples_d = {'a': 1, 'b': 1, 'c': -1, 'd': -1}
samples_a = [{'a': -1, 'b': -1, 'c': 1, 'd': 1}, {'a': -1, 'b': 1, 'c': 1, 'd': 1}]
states = [hybrid.State.from_samples(samples_d, bqm),
```

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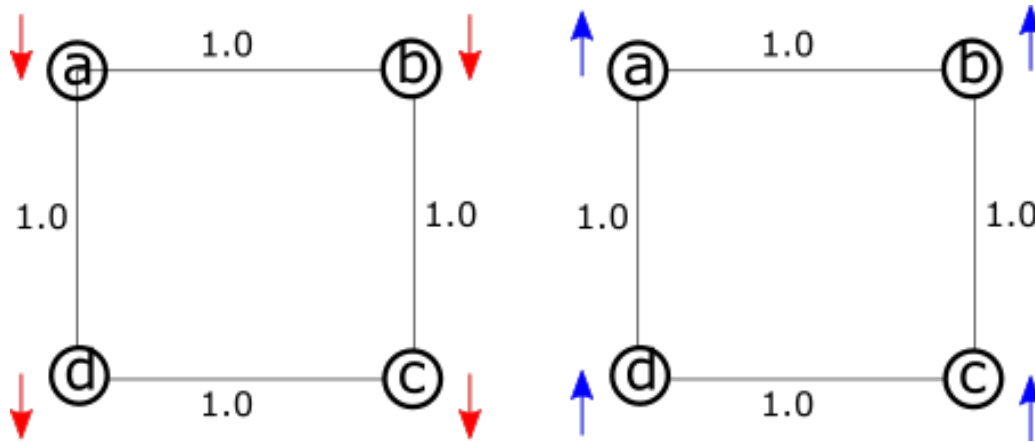


Fig. 6: Square problem with two ground states.

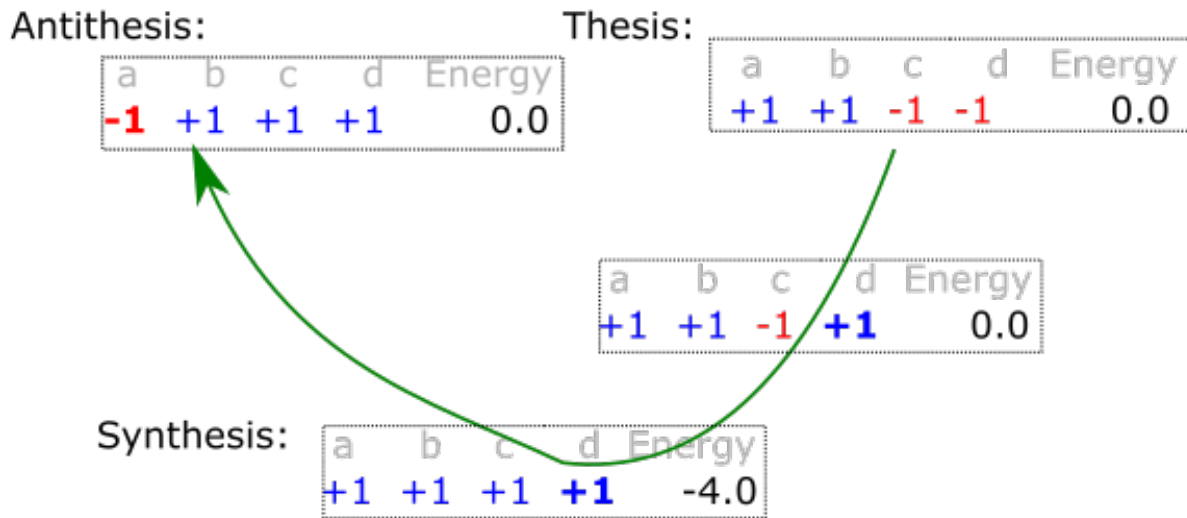


Fig. 7: Path from thesis to antithesis.

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```
hybrid.State.from_samples(samples_a, bqm)]
synthesis = GreedyPathMerge().next(states)
```

```
>>> print(synthesis.samples)
      a  b  c  d  energy  num_occ.
0  +1  +1  +1  +1    -4.0         1
[ 1 rows, 4 variables ]
```

## 2.2.4 Decomposers

### Classes

**class EnergyImpactDecomposer** (*size*, *min\_gain=None*, *rolling=True*, *rolling\_history=0.1*, *silent\_rewind=True*, *traversal='energy'*, *\*\*runopts*)

Selects a subproblem of variables maximally contributing to the problem energy.

The selection currently implemented does not ensure that the variables are connected in the problem graph.

#### Parameters

- **size** (*int*) – Nominal number of variables in the subproblem. Actual subproblem can be smaller, depending on other parameters (e.g. *min\_gain*).
- **min\_gain** (*int*, *optional*, *default=-inf*) – Minimum reduction required to BQM energy, given the current sample. A variable is included in the subproblem only if inverting its sample value reduces energy by at least this amount.
- **rolling** (*bool*, *optional*, *default=True*) – If True, successive calls for the same problem (with possibly different samples) produce subproblems on different variables, selected by rolling down the list of all variables sorted by decreasing impact.
- **rolling\_history** (*float*, *optional*, *default=0.1*) – Fraction of the problem size, as a float in range 0.0 to 1.0, that should participate in the rolling selection. Once reached, subproblem unrolling is reset.
- **silent\_rewind** (*bool*, *optional*, *default=True*) – If False, raises `EndOfStream` when resetting/rewinding the subproblem generator upon the reset condition for unrolling.
- **traversal** (*str*, *optional*, *default='energy'*) – Traversal algorithm used to pick a subproblem of *size* variables. Options are:
  - energy**: Use the next *size* variables in the list of variables ordered by descending energy impact.
  - bfs**: Breadth-first traversal seeded by the next variable in the energy impact list.
  - pfs**: Priority-first traversal seeded by variables from the energy impact list, proceeding with the variable on the search boundary that has the highest energy impact.

See [Examples](#).

**class IdentityDecomposer**

Selects a subproblem that is a full copy of the problem.

**class RandomConstraintDecomposer** (*size*, *constraints*, *\*\*runopts*)

Selects variables randomly as constrained by groupings.

By grouping related variables, the problem's structure can guide the random selection of variables so subproblems are related to the problem's constraints.

### Parameters

- **size** (*int*) – Number of variables in the subproblem.
- **constraints** (*list[set]*) – Groups of variables in the BQM, as a list of sets, where each set is associated with a constraint.

See *Examples*.

**class RandomSubproblemDecomposer** (*size*, *\*\*runopts*)

Selects a subproblem of *size* random variables.

The selection currently implemented does not ensure that the variables are connected in the problem graph.

**Parameters** **size** (*int*) – Number of variables in the subproblem.

See *Examples*.

**class RoofDualityDecomposer** (*sampling\_mode=True*, *\*\*runopts*)

Selects a subproblem with variables that cannot be fixed by roof duality.

Roof duality finds a lower bound for the minimum of a quadratic polynomial. It can also find minimizing assignments for some of the polynomial's variables; these fixed variables take the same values in all optimal solutions [BHT] [BH]. A quadratic pseudo-Boolean function can be represented as a network to find the lower bound through network-flow computations. This decomposer can also use maximum flow in the implication network to fix variables. Consequently, you can find an assignment for the remaining variables that attains the optimal value.

**Parameters** **sampling\_mode** (*bool, optional, default=True*) – In sampling mode, only roof-duality is used. When *sampling\_mode* is false, strongly connected components are used to fix more variables, but in some optimal solutions these variables may take different values.

**class TilingChimeraDecomposer** (*size=(4, 4, 4)*, *loop=True*, *\*\*runopts*)

Returns sequential Chimera lattices that tile the initial problem.

A Chimera lattice is an m-by-n grid of Chimera tiles, where each tile is a bipartite graph with shores of size t. The problem is decomposed into a sequence of subproblems with variables belonging to the Chimera lattices that tile the problem Chimera lattice. For example, a 2x2 Chimera lattice could be tiled 64 times (8x8) on a fully-yielded D-Wave 2000Q system (16x16).

### Parameters

- **size** (*int, optional, default=(4, 4, 4)*) – Size of the Chimera lattice as (m, n, t), where m is the number of rows, n the columns, and t the size of shore in the Chimera lattice.
- **loop** (*Bool, optional, default=True*) – Cycle continually through the tiles.

See *Examples*.

## Examples

### EnergyImpactDecomposer

This example iterates twice on a 10-variable binary quadratic model with a random initial sample set. *size* configuration limits the subproblem in the first iteration to the first 4 variables shown in the output of *flip\_energy\_gains*.



```
import dimod
from hybrid.decomposers import EnergyImpactDecomposer
from hybrid.core import State
from hybrid.utils import min_sample, flip_energy_gains

bqm = dimod.BinaryQuadraticModel({t: 0 for t in range(10)},
                                 {(t, (t+1) % 10): 1 for t in range(10)},
                                 0, 'BINARY')

decomposer = EnergyImpactDecomposer(size=4, rolling=True, rolling_history=1.0)
state0 = State.from_sample(min_sample(bqm), bqm)
```

```
>>> flip_energy_gains(bqm, state0.samples.first.sample)
[(0, 9), (0, 8), (0, 7), (0, 6), (0, 5), (0, 4), (0, 3), (0, 2), (0, 1), (0, 0)]
>>> state1 = decomposer.run(state0).result()
>>> list(state1.subproblem.variables)
[8, 7, 9, 6]
>>> state2 = decomposer.run(state1).result()
>>> list(state2.subproblem.variables)
[2, 3, 4, 5]
```

## RandomSubproblemDecomposer

This example decomposes a 6-variable binary quadratic model with a random initial sample set to create a 3-variable subproblem.

```
import dimod
from hybrid.decomposers import RandomSubproblemDecomposer
from hybrid.core import State
from hybrid.utils import random_sample

bqm = dimod.BinaryQuadraticModel(
    {t: 0 for t in range(6)}, {(t, (t+1) % 6): 1 for t in range(6)}, 0, 'BINARY')

decomposer = RandomSubproblemDecomposer(bqm, size=3)
state0 = State.from_sample(random_sample(bqm), bqm)
state1 = decomposer.run(state0).result()
```

```
>>> print(state1.subproblem)
BinaryQuadraticModel({2: 1.0, 3: 0.0, 4: 0.0}, {(2, 3): 1.0, (3, 4): 1.0}, 0.0,
↳ Vartype.BINARY)
```

## TilingChimeraDecomposer

This example decomposes a 2048-variable Chimera structured binary quadratic model read from a file into 2x2x4-lattice subproblems.

```
import dimod
from hybrid.decomposers import TilingChimeraDecomposer
from hybrid.core import State
from hybrid.utils import random_sample

with open('problems/random-chimera/2048.09.qubo', 'r') as fp:
```

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```
bqm = dimod.BinaryQuadraticModel.from_coo(fp)

decomposer = TilingChimeraDecomposer(size=(2,2,4))
state0 = State.from_sample(random_sample(bqm), bqm)
state1 = decomposer.run(state0).result()
```

```
>>> print(state1.subproblem)
BinaryQuadraticModel({0: 0.0, 4: 0.0, 5: 0.0, 6: 0.0, 7: -3.0, 1: 0.0, 2: 0.0, 3: -4.0,
↳0, 1024: -7.0, 1028: 0.0,
>>> # Snipped above response for brevity
>>> state1 = decomposer.run(state0).result()
>>> print(state1.subproblem)
BinaryQuadraticModel({8: 3.0, 12: 0.0, 13: 2.0, 14: -11.0, 15: -3.0, 9: 4.0, 10: 0.0,
↳11: 0.0, 1032: 0.0,
>>> # Snipped above response for brevity
```

## RandomConstraintDecomposer

This example decomposes a 4-variable binary quadratic model that represents three serial NOT gates into 2-variable subproblems. The expected decomposition should use variables that represent one of the NOT gates rather than two arbitrary variables.

```
import dimod
from hybrid.decomposers RandomConstraintDecomposer
from hybrid.core import State
from hybrid.utils import random_sample

bqm = dimod.BinaryQuadraticModel({'w': -2.0, 'x': -4.0, 'y': -4.0, 'z': -2.0},
                                  {'(w', 'x)': 4.0, ('x', 'y)': 4.0, ('y', 'z)': 4.0},
                                  3.0, 'BINARY')

decomposer = RandomConstraintDecomposer(2, [{'w', 'x'}, {'x', 'y'}, {'y', 'z'}])
state0 = State.from_sample(random_sample(bqm), bqm)
state1 = decomposer.run(state0).result()
```

```
>>> print(state1.subproblem)
BinaryQuadraticModel({'z': -2.0, 'y': 0.0}, {'(z', 'y)': 4.0}, 0.0, Vartype.BINARY)
```

## 2.2.5 Flow Structuring

Classes that structure (hybrid) workflows.

### Classes

**class ArgMin** (*key=None*, *\*\*runopts*)

Selects the best state from a sequence of *States*.

**Parameters** **key** (*callable/str*) – Best state is judged according to a metric defined with a *key*. The *key* can be a *callable* with a signature:

```
key :: (State s, Ord k) => s -> k
```

or a string holding a key name/path to be extracted from the input state with `operator.attrgetter` method.

By default, `key == operator.attrgetter('samples.first.energy')`, thus favoring states containing a sample with the minimal energy.

## Examples

This example runs two branches—a classical tabu search interrupted by samples of subproblems returned from a D-Wave system—and selects the state with the minimum-energy sample.

```
>>> RacingBranches (                               # doctest: +SKIP
    InterruptableTabuSampler(),
    EnergyImpactDecomposer(size=2)
    | QPUSubproblemAutoEmbeddingSampler()
    | SplatComposer()
) | ArgMin()
```

**class Branch** (*components=()*, *\*\*runopts*)

Sequentially executed *Runnable* components.

**Parameters** *components* (iterable of *Runnable*) – Complete processing sequence to update a current set of samples, such as: `decomposer | sampler | composer`.

**Input:** Defined by the first branch component.

**Output:** Defined by the last branch component.

## Examples

This example runs one iteration of a branch comprising a decomposer, local Tabu solver, and a composer. A 10-variable binary quadratic model is decomposed by the energy impact of its variables into a 6-variable subproblem to be sampled twice with a manually set initial state of all -1 values.

```
>>> import dimod                               # Create a binary quadratic model
>>> bqm = dimod.BQM({t: 0 for t in range(10)},
...                 {(t, (t+1) % 10): 1 for t in range(10)},
...                 0, 'SPIN')
>>> # Run one iteration on a branch
>>> branch = (EnergyImpactDecomposer(size=6, min_gain=-10) |
...          TabuSubproblemSampler(num_reads=2) |
...          SplatComposer())
>>> new_state = branch.next(State.from_sample(min_sample(bqm), bqm))
>>> print(new_state.subsamples)                 # doctest: +SKIP
    4  5  6  7  8  9  energy  num_occ.
0  +1 -1 -1 +1 -1 +1    -5.0      1
1  +1 -1 -1 +1 -1 +1    -5.0      1
[ 2 rows, 6 variables ]
```

**class Branches** (*\*branches*, *\*\*runopts*)

Runs multiple workflows of type *Runnable* in parallel, blocking until all finish.

Branches operates similarly to `Parallel`, but each branch runs on a separate input *State*.

**Parameters** *\*branches* (*[Runnable]*) – Runnable branches listed as positional arguments.

**Input:** *States*

**Output:** `States`

---

**Note:** `Branches` is also available via implicit parallelization binary operator `&`.

---

### Examples

This example runs two branches, a classical tabu search and a random sampler, until both terminate.

```
>>> Branches(TabuSubproblemSampler(), RandomSubproblemSampler()) # doctest: ↪
↪+SKIP
```

Alternatively:

```
>>> TabuSubproblemSampler() & RandomSubproblemSampler() # doctest: +SKIP
```

**class Lambda** (*next*, *error=None*, *init=None*, *\*\*runopts*)

Creates a runnable on fly, given just its *next* function (optionally *init* and *error* functions can be specified too).

#### Parameters

- **next** (*callable*) – Implementation of runnable’s *next* method, provided as a callable (usually a lambda expression for simple operations). Signature of the callable has to match the signature of *next()*; i.e., it accepts two arguments: runnable instance and state instance.
- **error** (*callable*) – Implementation of runnable’s *error* method. See *error()*.
- **init** (*callable*) – Implementation of runnable’s *init* method. See *init()*.

---

**Note:** Traits are not enforced, apart from the SISO requirement. Also, note *Lambda* runnables can only implement SISO systems.

---

### Examples

This example creates and runs a simple runnable that multiplies state variables *a* and *b*, storing them in *c*.

```
>>> Lambda(lambda _, s: s.updated(c=s.a * s.b)).run(State(a=2, b=3)).result()
↪# doctest: +SKIP
{'a': 2, 'b': 3, 'c': 6, ...}
```

This example applies  $x += 1$  to a sequence of input states.

```
>>> Map(Lambda(lambda _, s: s.updated(x=s.x + 1))).run(States(State(x=0), ↪
↪State(x=1))).result() # doctest: +SKIP
[{'problem': None, 'x': 1, 'samples': None}, {'problem': None, 'x': 2, 'samples': ↪
↪None}]
```

**class Loop** (*\*args*, *\*\*kwargs*)

Alias for *LoopUntilNoImprovement*.

**class LoopUntilNoImprovement** (*\*args*, *\*\*kwargs*)

Iterates *Runnable* for up to *max\_iter* times, or until a state quality metric, defined by the *key* function, shows no improvement for at least *convergence* number of iterations. Alternatively, maximum allowed runtime can be

defined with *max\_time*, or a custom termination Boolean function can be given with *terminate* (a predicate on *key*).

### Parameters

- **runnable** (*Runnable*) – A runnable that’s looped over.
- **max\_iter** (*int/None, optional, default=None*) – Maximum number of times the *runnable* is run, regardless of other termination criteria. This is the upper bound. By default, an upper bound on the number of iterations is not set.
- **convergence** (*int/None, optional, default=None*) – Terminates upon reaching this number of iterations with unchanged output. By default, convergence is not checked, so the only termination criteria is defined with *max\_iter*. Setting neither creates an infinite loop.
- **max\_time** (*float/None, optional, default=None*) – Wall clock runtime termination criterion. Unlimited by default.
- **key** (*callable/str*) – Best state is judged according to a metric defined with a *key*. *key* can be a *callable* with a signature:

```
key :: (State s, Ord k) => s -> k
```

or a string holding a key name/path to be extracted from the input state with *operator.attrgetter* method.

By default, *key == operator.attrgetter('samples.first.energy')*, thus favoring states containing a sample with the minimal energy.

- **terminate** (*callable, optional, default=None*) – Loop termination Boolean function (a predicate on *key* value):

```
terminate :: (Ord k) => k -> Bool
```

**class LoopWhileNoImprovement** (*runnable, max\_iter=None, max\_tries=None, max\_time=None, key=None, terminate=None, \*\*runopts*)

Iterates *Runnable* until a state quality metric, defined by the *key* function, shows no improvement for at least *max\_tries* number of iterations or until *max\_iter* number of iterations is exceeded. Alternatively, maximum allowed runtime can be defined with *max\_time*, or a custom termination Boolean function can be given with *terminate* (a predicate on *key*).

---

**Note:** Unlike *LoopUntilNoImprovement/Loop*, *LoopWhileNoImprovement* will run the loop body *runnable* with the **same input** if output shows no improvement (up to *max\_tries* times), and it will use the new output if it’s better than the input.

---

### Parameters

- **runnable** (*Runnable*) – A runnable that’s looped over.
- **max\_iter** (*int/None, optional, default=None*) – Maximum number of times the *runnable* is run, regardless of other termination criteria. This is the upper bound. By default, an upper bound on the number of iterations is not set.
- **max\_tries** (*int, optional, default=None*) – Maximum number of times the *runnable* is run for the **same** input state. On each improvement, the better state is used for the next input state, and the try/trial counter is reset. Defaults to an infinite loop (unbounded number of tries).

- **max\_time** (*float/None, optional, default=None*) – Wall clock runtime termination criterion. Unlimited by default.
- **key** (*callable/str*) – Best state is judged according to a metric defined with a *key*. *key* can be a *callable* with a signature:

```
key :: (State s, Ord k) => s -> k
```

or a string holding a key name/path to be extracted from the input state with *operator.attrgetter* method.

By default, *key == operator.attrgetter('samples.first.energy')*, thus favoring states containing a sample with the minimal energy.

- **terminate** (*callable, optional, default=None*) – Loop termination Boolean function (a predicate on *key* value):

```
terminate :: (Ord k) => k -> Bool
```

**class Map** (*runnable, \*\*runopts*)

Runs a specified *Runnable* in parallel on all input states.

**Parameters** **runnable** (*Runnable*) – A runnable executed for every input state.

### Examples

This example runs *TabuProblemSampler* on two input states in parallel, returning when both are done.

```
>>> states = States(State(problem=bqm1), State(problem=bqm2)) # doctest: +SKIP
>>> Map(TabuProblemSampler()).run(states).result() # doctest: +SKIP
[<state_1_with_solution>, <state_2_with_solution>]
```

**class ParallelBranches** (*\*branches, \*\*runopts*)

Runs multiple workflows of type *Runnable* in parallel, blocking until all finish.

Parallel/ParallelBranches operates similarly to *Branches*, but every branch re-uses the same input *State*.

**Parameters** **\*branches** (*[Runnable]*) – Comma-separated branches.

**Input:** *State*

**Output:** *States*

---

**Note:** *Parallel* is implemented as:

```
Parallel(*branches) := Dup(len(branches)) | Branches(*branches)
```

---

**Note:** *ParallelBranches* is also available as *Parallel*.

---

### Examples

This example runs two branches, a classical tabu search and a random sampler, until both terminate.

```
>>> Parallel(                                     # doctest: +SKIP
    TabuSubproblemSampler(),
    RandomSubproblemSampler()
) | ArgMin()
```

**class RacingBranches** (\*branches, \*\*runopts)

Runs (races) multiple workflows of type *Runnable* in parallel, stopping all once the first finishes. Returns the results of all, in the specified order.

**Parameters** \*branches ([*Runnable*]) – Comma-separated branches.

**Note:** Each branch runnable is called with run option `racing_context=True`, so it can adapt its behaviour to the context.

**Note:** *RacingBranches* is also available as *Race*.

## Examples

This example runs two branches: a classical tabu search interrupted by samples of subproblems returned from a D-Wave system.

```
>>> RacingBranches(                               # doctest: +SKIP
    InterruptableTabuSampler(),
    EnergyImpactDecomposer(size=2)
    | QPUSubproblemAutoEmbeddingSampler()
    | SplatComposer()
) | ArgMin()
```

**class Reduce** (runnable, initial\_state=None, \*\*runopts)

Fold-left using the specified *Runnable* on a sequence of input states, producing a single output state.

### Parameters

- **runnable** (*Runnable*) – A runnable used as the fold-left operator. It should accept a 2-State input and produce a single State on output.
- **initial\_state** (State, optional, default=None) – Optional starting state into which input states will be folded in. If undefined, the first input state is used as the *initial\_state*.

**class TrackMin** (key=None, output=False, input\_key='samples', output\_key='best\_samples', \*\*runopts)

Tracks and records the best *State* according to a metric defined with a *key* function; typically this is the minimal state.

### Parameters

- **key** (callable/str, optional, default=None) – Best state is judged according to a metric defined with a *key*. *key* can be a *callable* with a signature:

```
key :: (State s, Ord k) => s -> k
```

or a string holding a key name/path to be extracted from the input state with *operator.attrgetter* method.

By default, `key == operator.attrgetter('samples.first.energy')`, thus favoring states containing a sample with the minimal energy.

- **output** (*bool*, optional, default=False) – Update the output state’s *output\_key* with the *input\_key* of the best state seen so far.
- **input\_key** (*str*, optional, default='samples') – If *output=True*, then this defines the variable/key name in the input state that shall be included in the output state.
- **output\_key** (*str*, optional, default='best\_samples') – If *output=True*, then the key under which the *input\_key* from the best state seen so far is stored in the output state.

**class Unwind** (*runnable*, *\*\*runopts*)

Iterates *Runnable* until *EndOfStream* is raised, collecting all output states along the way.

---

**Note:** the child runnable is called with run option *silent\_rewind=False*, and it is expected to raise *EndOfStream* on unwind completion.

---

**class Dup** (*n*, *\*args*, *\*\*kwargs*)

Duplicates input *State*, *n* times, into output *States*.

## Methods

See *Primitives* for methods inherited from the *Runnable* superclass.

## 2.2.6 Utilities

### Methods

<i>bqm_edges_between_variables</i> (bqm, variables)	Return edges connecting specified variables of a binary quadratic model.
<i>bqm_induced_by</i> (bqm, variables, sample)	Induce a binary quadratic model by fixing values of boundary variables.
<i>bqm_reduced_to</i> (bqm, variables, sample[...])	Reduce a binary quadratic model by fixing values of some variables.
<i>chimera_tiles</i> (bqm, m, n, t)	Map a binary quadratic model to a set of Chimera tiles.
<i>flip_energy_gains</i> (bqm, sample[, variables, ...])	Order variable flips by descending contribution to energy changes in a BQM.
<i>max_sample</i> (bqm)	Return a sample with all variables set to the maximal value for a binary quadratic model.
<i>min_sample</i> (bqm)	Return a sample with all variables set to the minimal value for a binary quadratic model.
<i>random_sample</i> (bqm)	Return a random sample for a binary quadratic model.
<i>random_sample_seq</i> (size, vartype)	Return a random sample.
<i>sample_as_dict</i> (sample)	Return sample object in dict format.
<i>sample_as_list</i> (sample)	Return sample object in list format.
<i>select_localsearch_adversaries</i> (bqm, sample)	Find variable flips that contribute high energy changes to a BQM.
<i>select_random_subgraph</i> (bqm, n)	Select randomly <i>n</i> variables of the specified binary quadratic model.
<i>updated_sample</i> (sample, replacements)	Update a copy of a sample with replacement values.



## hybrid.utils.bqm\_edges\_between\_variables

**bqm\_edges\_between\_variables** (*bqm*, *variables*)

Return edges connecting specified variables of a binary quadratic model.

### Parameters

- **bqm** (`dimod.BinaryQuadraticModel`) – Binary quadratic model (BQM).
- **variables** (*list/set*) – Subset of variables in the BQM.

**Returns** All edges connecting *variables* as tuples plus the variables themselves as tuples (*v*, *v*).

**Return type** `list`

### Examples

This example returns connecting edges between 3 nodes of a BQM based on a 4-variable path graph.

```
>>> import dimod
>>> bqm = dimod.BQM({}, {(0, 1): 1, (1, 2): 1, (2, 3): 1}, 0, 'BINARY')
>>> bqm_edges_between_variables(bqm, {0, 1, 3})
[(0, 1), (0, 0), (1, 1), (3, 3)]
```

## hybrid.utils.bqm\_induced\_by

**bqm\_induced\_by** (*bqm*, *variables*, *sample*)

Induce a binary quadratic model by fixing values of boundary variables.

The function is optimized for `len(variables) << len(bqm)`, that is, for fixing the majority of variables.

### Parameters

- **bqm** (`dimod.BinaryQuadraticModel`) – Binary quadratic model (BQM).
- **variables** (*list/set*) – Subset of variables to keep in the reduced BQM, typically a subgraph.
- **sample** (*dict/list*) – Mapping of variable labels to values or a list when labels are sequential integers. Values are required only for boundary variables, that is, for variables with interactions with *variables* (having edges with non-zero quadratic biases connected to the subgraph).

**Returns** A BQM induced by fixing values of those variables adjacent to its subset of variables and setting the energy offset to zero.

**Return type** `dimod.BinaryQuadraticModel`

### Examples

This example induces a 2-variable BQM from a 6-variable path graph—the subset of nodes 2 and 3 of nodes 0 to 5—by fixing values of boundary variables 1 and 4.

```
>>> import dimod
>>> import networkx as nx
>>> bqm = dimod.BinaryQuadraticModel({},
...     {edge: edge[0] + 0.5 for edge in set(nx.path_graph(6).edges)}, 0, 'BINARY
...     !)
```

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```
>>> sample = {1: 3, 4: 3}
>>> bqm_induced_by(bqm, [2, 3], sample)
BinaryQuadraticModel({2: 4.5, 3: 10.5}, {(2, 3): 2.5}, 0.0, Vartype.BINARY)
```

### hybrid.utils.bqm\_reduced\_to

**bqm\_reduced\_to** (*bqm*, *variables*, *sample*, *keep\_offset=True*)

Reduce a binary quadratic model by fixing values of some variables.

The function is optimized for  $\text{len}(\text{variables}) \sim \text{len}(\text{bqm})$ , that is, for small numbers of fixed variables.

#### Parameters

- **bqm** (*dimod.BinaryQuadraticModel*) – Binary quadratic model (BQM).
- **variables** (*list/set*) – Subset of variables to keep in the reduced BQM.
- **sample** (*dict/list*) – Mapping of variable labels to values or a list when labels are sequential integers. Must include all variables not specified in *variables*.
- **keep\_offset** (*bool, optional, default=True*) – If false, set the reduced binary quadratic model’s offset to zero; otherwise, uses the calculated energy offset.

**Returns** A reduced BQM.

**Return type** `dimod.BinaryQuadraticModel`

### Examples

This example reduces a 3-variable BQM to two variables.

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': -1, 'bc': -1, 'ca': -1}, 0, 'BINARY')
>>> sample = {'a': 1, 'b': 1, 'c': 0}
>>> bqm_reduced_to(bqm, ['a', 'b'], sample)
BinaryQuadraticModel({'a': 0, 'b': 0}, {('a', 'b'): -1}, 0, Vartype.BINARY)
```

### hybrid.utils.chimera\_tiles

**chimera\_tiles** (*bqm*, *m*, *n*, *t*)

Map a binary quadratic model to a set of Chimera tiles.

A Chimera lattice is an *m*-by-*n* grid of Chimera tiles, where each tile is a bipartite graph with shores of size *t*.

#### Parameters

- **bqm** (*BinaryQuadraticModel*) – Binary quadratic model (BQM).
- **m** (*int*) – Rows.
- **n** (*int*) – Columns.
- **t** (*int*) – Size of shore.

**Returns** Map as a dict where keys are tile coordinates (row, column, aisle) and values are partial embeddings of part of the BQM to a Chimera tile. Embeddings are those that would be generated by `dwave_networkx`’s `chimera_graph()` function.

Return type `dict`

## Examples

This example maps a 1-by-2 Chimera-derived BQM to 2 side-by-side tiles.

```
>>> import dwave_networkx as dnx
>>> import dimod
>>> G = dnx.chimera_graph(1, 2)      # Create a Chimera-based BQM
>>> bqm = dimod.BinaryQuadraticModel({}, {edge: edge[0] for edge in G.edges}, 0,
↳ 'BINARY')
>>> chimera_tiles(bqm, 1, 1, 4)     # doctest: +SKIP
{(0, 0, 0): {0: [0], 1: [1], 2: [2], 3: [3], 4: [4], 5: [5], 6: [6], 7: [7]},
 (0, 1, 0): {8: [0], 9: [1], 10: [2], 11: [3], 12: [4], 13: [5], 14: [6], 15: [7]}
↳ }
```

## hybrid.utils.flip\_energy\_gains

**flip\_energy\_gains** (*bqm*, *sample*, *variables=None*, *min\_gain=None*)

Order variable flips by descending contribution to energy changes in a BQM.

### Parameters

- **bqm** (`dimod.BinaryQuadraticModel`) – Binary quadratic model (BQM).
- **sample** (*list/dict*) – Sample values as returned by dimod samplers (0 or 1 values for `dimod.BINARY` and -1 or +1 for `dimod.SPIN`)
- **variables** (*sequence, optional, default=None*) – Consider only flips of these variables. If undefined, consider all variables in *sample*.
- **min\_gain** (*float, optional, default=None*) – Minimum required energy increase from flipping a sample value to return its corresponding variable.

### Returns

Energy changes in descending order, in the format of tuples (energy\_gain, variable), for flipping the given sample value for each variable.

Return type `list`

## Examples

This example returns connecting edges between 3 nodes of a BQM based on a 4-variable path graph.

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': 0, 'bc': 1, 'cd': 2}, 0, 'SPIN')
>>> flip_energy_gains(bqm, {'a': -1, 'b': 1, 'c': 1, 'd': -1})
[(4, 'd'), (2, 'c'), (0, 'a'), (-2, 'b')]
```

## hybrid.utils.max\_sample

**max\_sample** (*bqm*)

Return a sample with all variables set to the maximal value for a binary quadratic model.

Parameters **bqm** (`BinaryQuadraticModel`) – Binary quadratic model (BQM).

**Returns** A sample with maximal values for all variables of the BQM.

**Return type** `dict`

### Examples

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': -1, 'bc': -1, 'ca': -1}, 0, 'BINARY')
>>> max_sample(bqm)      # doctest: +SKIP
{'a': 1, 'b': 1, 'c': 1}
```

### hybrid.utils.min\_sample

**min\_sample** (*bqm*)

Return a sample with all variables set to the minimal value for a binary quadratic model.

**Parameters** `bqm` (`BinaryQuadraticModel`) – Binary quadratic model (BQM).

**Returns** A sample with minimal values for all variables of the BQM.

**Return type** `dict`

### Examples

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': -1, 'bc': -1, 'ca': -1}, 0, 'BINARY')
>>> min_sample(bqm)     # doctest: +SKIP
{'a': 0, 'b': 0, 'c': 0}
```

### hybrid.utils.random\_sample

**random\_sample** (*bqm*)

Return a random sample for a binary quadratic model.

**Parameters** `bqm` (`BinaryQuadraticModel`) – Binary quadratic model (BQM).

**Returns** A sample with random values for the BQM.

**Return type** `dict`

### Examples

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': -1, 'bc': -1, 'ca': -1}, 0, 'BINARY')
>>> random_sample(bqm)  # doctest: +SKIP
{'a': 0, 'b': 1, 'c': 1}
```

### hybrid.utils.random\_sample\_seq

**random\_sample\_seq** (*size*, *vartype*)

Return a random sample.

**Parameters**

- **size** (*int*) – Sample size (number of variables).
- **vartype** (*dimod.Vartype*) – Variable type; for example, *Vartype.SPIN*, *BINARY*, or *{-1, 1}*.

**Returns** Random sample of *size* in length, with values from *vartype*.

**Return type** *dict*

**Examples**

```
>>> random_sample_seq(4, dimod.BINARY)      # doctest: +SKIP
{0: 0, 1: 1, 2: 0, 3: 0}
```

**hybrid.utils.sample\_as\_dict**

**sample\_as\_dict** (*sample*)

Return sample object in dict format.

**Parameters**

- **sample** (*list/dict/dimod.SampleView*) – Sample object formatted as a list,
- **array, dict, or as returned by dimod samplers.** (*Numpy*) –

**Returns** Copy of *sample* formatted as a dict, with variable indices as keys.

**Return type** *list*

**Examples**

```
>>> sample = [1, 2, 3]
>>> sample_as_dict(sample)      # doctest: +SKIP
{0: 1, 1: 2, 2: 3}
```

**hybrid.utils.sample\_as\_list**

**sample\_as\_list** (*sample*)

Return sample object in list format.

**Parameters**

- **sample** (*list/dict/dimod.SampleView*) – Sample object formatted as a list,
- **array, dict, or as returned by dimod samplers. Variable labeling** (*Numpy*) –
- **be numerical.** (*must*) –

**Returns** Copy of *sample* formatted as a list.

**Return type** *list*

## Examples

```
>>> sample = {0: 1, 1: 1}
>>> sample_as_list(sample)
[1, 1]
```

## hybrid.utils.select\_localsearch\_adversaries

**select\_localsearch\_adversaries** (*bqm, sample, max\_n=None, min\_gain=None*)

Find variable flips that contribute high energy changes to a BQM.

### Parameters

- **bqm** (*dimod.BinaryQuadraticModel*) – Binary quadratic model (BQM).
- **sample** (*list/dict*) – Sample values as returned by dimod samplers (0 or 1 values for *dimod.BINARY* and -1 or +1 for *dimod.SPIN*)
- **max\_n** (*int, optional, default=None*) – Maximum contributing variables to return. By default, returns any variable for which flipping its sample value results in an energy gain of *min\_gain*.
- **min\_gain** (*float, optional, default=None*) – Minimum required energy increase from flipping a sample value to return its corresponding variable.

**Returns** Up to *max\_n* variables for which flipping the corresponding sample value increases the BQM energy by at least *min\_gain*.

**Return type** *list*

## Examples

This example returns 2 variables (out of up to 3 allowed) for which flipping sample values changes BQM energy by 1 or more. The BQM has energy gains of 0, -2, 2, 4 for variables a, b, c, d respectively for the given sample.

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': 0, 'bc': 1, 'cd': 2}, 0, 'SPIN')
>>> select_localsearch_adversaries(
...     bqm, {'a': -1, 'b': 1, 'c': 1, 'd': -1}, max_n=3, min_gain=1)
['d', 'c']
```

## hybrid.utils.select\_random\_subgraph

**select\_random\_subgraph** (*bqm, n*)

Select randomly *n* variables of the specified binary quadratic model.

### Parameters

- **bqm** (*dimod.BinaryQuadraticModel*) – Binary quadratic model (BQM).
- **n** (*int*) – Number of requested variables. Must be between 0 and *len(bqm)*.

**Returns** *n* variables selected randomly from the BQM.

**Return type** *list*

## Examples

This example returns 2 variables of a 4-variable BQM.

```
>>> import dimod
>>> bqm = dimod.BQM({}, {'ab': 0, 'bc': 1, 'cd': 2}, 0, 'BINARY')
>>> select_random_subgraph(bqm, 2)      # doctest: +SKIP
['d', 'b']
```

## hybrid.utils.updated\_sample

**updated\_sample** (*sample*, *replacements*)

Update a copy of a sample with replacement values.

### Parameters

- **sample** (*list/dict*) – Sample values as returned by dimod samplers to be copied.
- **replacements** (*list/dict*) – Sample values to replace in the copied *sample*.

**Returns** Copy of *sample* overwritten by specified values.

**Return type** list/dict

## Examples

```
>>> sample = {'a': 1, 'b': 1}
>>> updated_sample(sample, {'b': 2})      # doctest: +SKIP
{'a': 1, 'b': 2}
```

## 2.2.7 Dimod Conversion

These classes handle conversion between *dwave-hybrid* *Runnable* classes and *dimod* samplers.

### Classes

**class HybridSampler** (*workflow*)

Produces a *dimod.Sampler* from a *hybrid.Runnable*-based sampler.

**Parameters** *workflow* (*Runnable*) – Hybrid workflow, likely composed, that accepts a binary quadratic model in the input state and produces sample(s) in the output state.

### Example

This example produces a *dimod* sampler from *TabuProblemSampler* and uses its *sample\_ising* mixin to solve a simple Ising problem.

```
>>> hybrid_sampler = TabuProblemSampler()
>>> dimod_sampler = HybridSampler(hybrid_sampler)
>>> solution = dimod_sampler.sample_ising({}, {'ab': 0.5, 'bc': 0.5, 'ca': 0.5})
>>> solution.first.energy
-0.5
```

**class HybridRunnable** (*sampler, fields, \*\*sample\_kwargs*)

Produces a *hybrid.Runnable* from a *dimod.Sampler* (dual of *HybridSampler*).

The runnable samples from a problem defined in a state field named *fields[0]* and populates the state field referred to by *fields[1]*.

#### Parameters

- **sampler** (*dimod.Sampler*) – dimod-compatible sampler which is run on every iteration of the runnable.
- **fields** (*tuple(str, str)*) – Input and output state field names.
- **\*\*sample\_kwargs** (*dict*) – Sampler-specific parameters passed to sampler on every call.

#### Example

This example creates a *Runnable* from dimod sampler *TabuSampler*, runs it on an Ising model, and finds the lowest energy.

```
>>> from tabu import TabuSampler
>>> import dimod
>>> bqm = dimod.BinaryQuadraticModel.from_ising({}, {'ab': 0.5, 'bc': 0.5, 'ca': 0.5})
>>> runnable = HybridRunnable(TabuSampler(), fields=('subproblem', 'subsamples'),
                               timeout=100)
>>> state0 = State(subproblem=bqm, subsamples=SampleSet.from_samples_bqm(min_
                               sample(bqm), bqm))
>>> state = runnable.run(state0)
>>> state.result()['subsamples'].first.energy      # doctest: +SKIP
-0.5
```

**class HybridProblemRunnable** (*sampler, \*\*sample\_kwargs*)

Produces a *hybrid.Runnable* from a *dimod.Sampler* (dual of *HybridSampler*).

The runnable that samples from *state.problem* and populates *state.samples*.

See an example in *hybrid.core.HybridRunnable*. An example of the duality with *HybridSampler* is:

```
HybridProblemRunnable(HybridSampler(TabuProblemSampler())) == TabuProblemSampler()
```

**class HybridSubproblemRunnable** (*sampler, \*\*sample\_kwargs*)

Produces a *hybrid.Runnable* from a *dimod.Sampler* (dual of *HybridSampler*).

The runnable that samples from *state.subproblem* and populates *state.subsamples*.

See an example in *hybrid.core.HybridRunnable*.

## 2.2.8 Traits

State traits are verified for all *Runnable* objects that inherit from *StateTraits* or its subclasses. Verification includes:

- (1) Minimal checks of workflow construction (composition of *Runnable* classes)
- (2) Runtime checks



All built-in *Runnable* classes declare state traits requirements that are either independent (for simple ones) or derived from a child workflow. Traits of a new *Runnable* must be expressed and modified at construction time by its parent. When developing new *Runnable* classes, constructing composite traits can be nontrivial for some advanced flow-control runnables. State traits validation base class and related state validation mixins (i/o validation toggle, i/o dimensionality, state structure).

When subclassing (combining with *Runnable*), list them in the following order, left to right:

- structure mixins (e.g. *SubsamplesIntaking* and *SubproblemSampler*)
- dimensionality mixins (e.g. *MultiInputStates* and *MISO*)
- validation toggles (e.g. *InputValidated* and *NotValidated*)
- StateTraits base class (not required if any of the above is used)
- Runnable base class

For example:

```
class MyRunnable(hybrid.traits.SubsamplesIntaking, hybrid.traits.MISO, hybrid. Runnable): pass

class EmbeddingIntaking
class EmbeddingProducing
class InputNotValidated
class InputValidated
class MIMO
    Multiple Inputs, Multiple Outputs.
class MISO
    Multiple Inputs, Single Output.
class MultiInputStates
class MultiOutputStates
class NotValidated
    Input state(s) and output state(s) are not validated.
class OutputNotValidated
class OutputValidated
class ProblemDecomposer
class ProblemIntaking
class ProblemProducing
class ProblemSampler
class SIMO
    Single Input, Multiple Outputs.
class SISO
    Single Input, Single Output.
class SamplesIntaking
class SamplesProcessor
class SamplesProducing
class SingleInputState
```

```
class SingleOutputState
class StateTraits
    Set of traits imposed on State. By default, not validated.
        validate_state_trait (state, trait, io)
            Validate single input/output (io) state trait.
class SubproblemIntaking
class SubproblemProducing
class SubproblemSampler
class SubsamplesComposer
class SubsamplesIntaking
class SubsamplesProcessor
class SubsamplesProducing
class Validated
    Validated input state(s) and output state(s).
```

### 2.2.9 Exceptions

```
exception EndOfStream
    Signals end of stream for streaming runnables.
exception InvalidStateError
    General state error.
exception RunnableError (message, state)
    Generic Runnable exception error that includes the error context, in particular, the State that caused the runnable component to fail.
exception StateDimensionalityError
    Single state expected instead of a state sequence, or vice versa.
exception StateTraitMissingError
    State missing a trait.
```

## 2.3 Installation

Install from a package on PyPI:

```
pip install dwave-hybrid
```

or from source:

```
git clone https://github.com/dwavesystems/dwave-hybrid.git
cd dwave-hybrid
pip install -r requirements.txt
python setup.py install
```

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